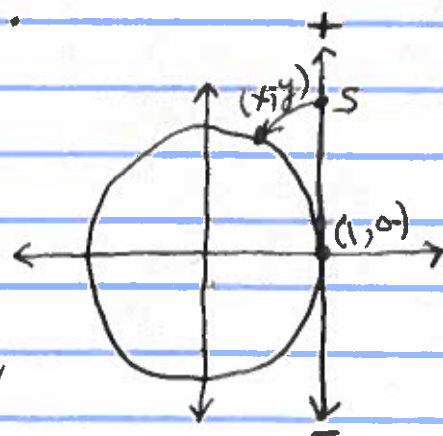


Section 3.3

1. To deal with trig functions in calculus, we must treat them as functions of real numbers rather than angles. The issue then is how to treat an angle like a real number.
2. Recall that when computing trig functions of an angle in standard position, we can use any point on the terminal side of θ due to similar triangles. Therefore we choose to use the point 1 unit from the origin (at the intersection of the terminal side of θ with the unit circle).

3. In a coordinate system, construct the unit circle (center at $(0,0)$ and radius $=1$) and the vertical line $x=1$ through the point $(1,0)$.

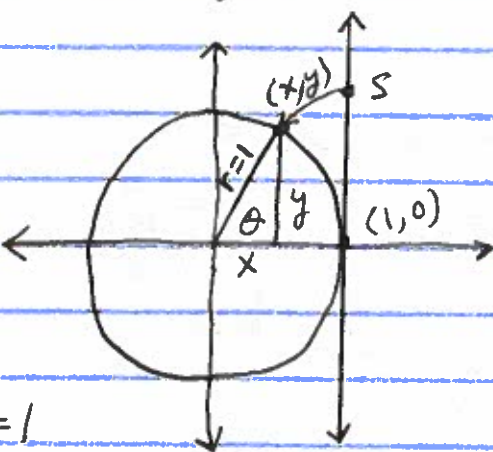


Make the line $x=1$ a "number line" by defining the origin 0 at the point $(1,0)$ in the coordinate system, positive direction up, and negative direction down.

On this vertical number line, locate a real number " s ". Then wrap that end of the number line around the unit circle until the number " s " falls on the unit circle at a point (x,y) relative to the coordinate system.

Define $\sin(s) = y$, $\cos(s) = x$, $\tan(s) = \frac{y}{x}$,
 $\cot(s) = \frac{x}{y}$, $\sec(s) = \frac{1}{x}$, and $\csc(s) = \frac{1}{y}$.

Now construct the ray from $(0,0)$ through (x,y) , forming an angle θ relative to the positive x -axis. Note that θ is in standard position. Form the reference Δ with side $x, y, r=1$ by dropping a vertical from (x,y) to $(x,0)$ on the x -axis.



$$\text{Then } \sin \theta = \frac{y}{r} = \frac{y}{1} = y = \sin(s),$$

$$\cos \theta = \frac{x}{r} = \frac{x}{1} = x = \cos(s),$$

$$\tan \theta = \frac{y}{x} = \tan(s), \quad \cot \theta = \frac{x}{y} = \cot(s),$$

$$\sec \theta = \frac{r}{x} = \frac{1}{x} = \sec(s), \quad \csc \theta = \frac{r}{y} = \frac{1}{y} = \csc(s).$$

Thus each trig function of θ equals the same trig function of s . Note also that " s " forms the arclength on the unit circle from $(1,0)$ to (x,y) . So relative to θ in radians, we have $s = r\theta = 1 \cdot \theta = \theta$.

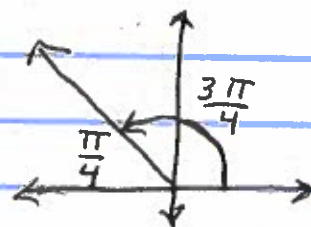
Thus any trig function of a real number " s " is the same as that trig function of the angle $\theta = s$ radians. Hence an angle in radians can be considered a real number.

Table of Exact Trigonometric Values

θ (rad / deg)	$0 = 0^\circ$	$\frac{\pi}{6} = 30^\circ$	$\frac{\pi}{4} = 45^\circ$	$\frac{\pi}{3} = 60^\circ$	$\frac{\pi}{2} = 90^\circ$
$\sin \theta$	0	$\frac{1}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{3}}{2}$	1
$\cos \theta$	1	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{2}}{2}$	$\frac{1}{2}$	0
$\tan \theta$	0	$\frac{\sqrt{3}}{3}$	1	$\sqrt{3}$	∞
$\cot \theta$	∞	$\sqrt{3}$	1	$\frac{\sqrt{3}}{3}$	0
$\sec \theta$	1	$\frac{2\sqrt{3}}{3}$	$\sqrt{2}$	2	∞
$\csc \theta$	∞	2	$\sqrt{2}$	$\frac{2\sqrt{3}}{3}$	1

4. Examples:

(a) To compute the exact value of the tangent of the real number $\frac{3\pi}{4}$, interpret $\frac{3\pi}{4}$ as an "angle" of $\frac{3\pi}{4}$ radians and proceed as we have done before. Drawing $\frac{3\pi}{4}$ in standard position, we get a reference angle of $\frac{\pi}{4}$. From the Table of Exact Values, $\tan \frac{\pi}{4} = 1$. Finally, $\tan \theta < 0$ in QII. Thus $\tan \frac{3\pi}{4} = -1$.



(b) For real numbers (angles in radians) not in the Table of Exact Values, use the calculator. For the sine of the real number -4.1 , simply put the calculator in radian mode and compute $\sin(-4.1) = 0.8182771111$.

5. Solving trig equations for real number solutions is also performed exactly as before. We simply find the "angle solutions" in radians, which are precisely the real number solutions.

Examples:

(a) Solve $2\sin X + \sqrt{3} = 0$ for real numbers X , $0 \leq X < 2\pi$.

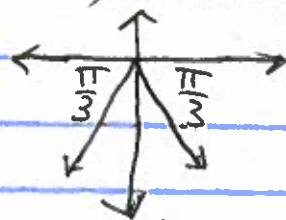
$$2\sin X + \sqrt{3} = 0 \Rightarrow 2\sin X = -\sqrt{3} \Rightarrow \sin X = -\frac{\sqrt{3}}{2}$$

Looking across the sine row in the Table of Exact Values, we locate $\frac{\sqrt{3}}{2}$ (ignoring the minus sign). Then moving up to the top row we find $\frac{\pi}{3}$. Thus the reference angle in radians is $X_{\text{ref}} = \frac{\pi}{3}$.

Since $-\frac{\sqrt{3}}{2} < 0$ and $\sin \theta < 0$ in Q_{III} & Q_{IV} , then draw $X_{\text{ref}} = \frac{\pi}{3}$ in Q_{III} & Q_{IV} .

Measuring these counter-clockwise from the positive X -axis, we get

$X = \frac{4\pi}{3}, \frac{5\pi}{3}$, which are the solutions sought.



(b) Solve $2\tan X - 2.2 = 0$ for real numbers X , $0 \leq X < 2\pi$.

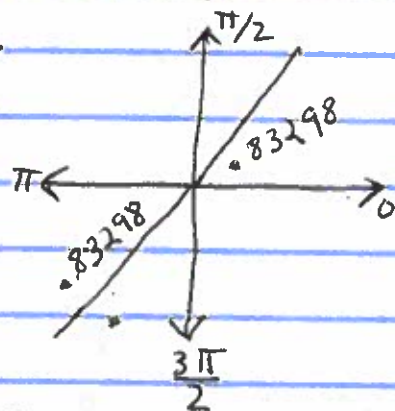
$$2\tan X - 2.2 = 0 \Rightarrow 2\tan X = 2.2 \Rightarrow \tan X = \frac{2.2}{2} = 1.1$$

Then $X_{\text{ref}} = \tan^{-1}(1.1) \approx .83298$ (rounded).

Since $\tan X = 1.1 > 0$ and $\tan \theta > 0$ in Q_I & Q_{III} , then draw $X_{\text{ref}} = .83298$ in Q_I & Q_{III} .

Measuring these counter-clockwise from the positive X -axis, we have

$X = .83298$ and $X = \pi + .83298 = 3.97457$.



Thus $X = .83298, 3.97457$ are the (approximate) solutions for $0 \leq X < 2\pi$.

(c) Solve $3\sec x + 6.9 = 0$ for real numbers x , $0 \leq x < 2\pi$.

$$3\sec x + 6.9 = 0 \Rightarrow 3\sec x = -6.9 \Rightarrow \sec x = \frac{-6.9}{3} \Rightarrow$$

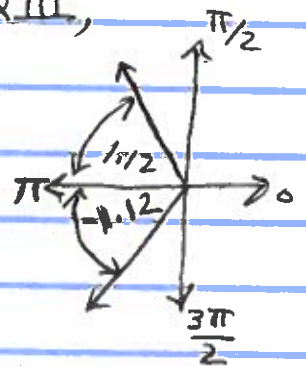
$$\sec x = -2.3 \Rightarrow \cos x = \frac{1}{\sec x} = -\frac{1}{2.3}.$$

Ignoring the minus sign, $x_{\text{ref}} = \cos^{-1}\left(\frac{1}{2.3}\right) \approx 1.12$.

Since $\cos x = -\frac{1}{2.3} < 0$ and $\cos \theta < 0$ in QII & QIII, then draw $x_{\text{ref}} = 1.12$ rad in QII & QIII.

Measuring these counter-clockwise from the positive x -axis, we have

$$x = \pi - 1.12 \approx 2.02 \text{ and } x = \pi + 1.12 \approx 4.26.$$



Thus $x = 2.02, 4.26$ are the (approximate) solutions sought.

Note: In determining the quadrants in which to draw x_{ref} , we used the fact that $\cos x = -\frac{1}{2.3} < 0$ and $\cos \theta < 0$ in QII & QIII. We could also have used $\sec x = -2.3$ and $\sec \theta < 0$ in QII & QIII.

Either approach is valid since $\cos \theta$ and $\sec \theta$ are reciprocals, and reciprocals always have the same sign (both positive or both negative).